

UNIVERSITY OF SOUTH FLORIDA

Defense of Master's Thesis

Trilateration-Based Localization in Known Environments with Object
Detection
by
Valeria Salas

For the M.S. Degree in Computer Engineering

Many strategies for localization have been proposed, the majority of which rely on distance measurements and estimates. The proposed approach is a method that combines image-based localization techniques and the principle of trilateration to perform localization in a known indoor environment using a camera, the proposed system can detect custom objects using object detection in the environment and calculate an approximation of the camera's position. To recognize the local environment and calculate an approximation of the camera's position, input data such as the size of the environment and the coordinates and sizes of the objects in the environment were given as input to the system together with the distance to such objects calculated by a previously calibrated distance detection algorithm.

Friday, October 2nd, 2021

11:00AM

Online (Microsoft Teams)

Please email for more information

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THE PUBLIC IS INVITED

Examining Committee

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